

Structural Form

$$\begin{array}{l} \text{Demand :} \\ \text{Supply:} \end{array} \quad \begin{array}{l} q_t = \alpha_1 p_t + \alpha_2 x_t + \epsilon_{dt} \\ q_t = \beta_1 p_t + \epsilon_{st} \end{array}$$

Reduced Form

$$p_t = \frac{\alpha_2 x_t}{\beta_1 - \alpha_1} + \frac{\epsilon_{dt} - \epsilon_{st}}{\beta_1 - \alpha_1} = \pi_1 x_t + v_{1t}$$

$$q_t = \frac{\beta_1 \alpha_2 x_t}{\beta_1 - \alpha_1} + \frac{\beta_1 \epsilon_{dt} - \alpha_1 \epsilon_{st}}{\beta_1 - \alpha_1} = \pi_2 x_t + v_{2t}$$

$$\beta_1 = \frac{\pi_2}{\pi_1} \quad \alpha_1 = ? \quad \alpha_2 = ?$$

Structural Form

$$\begin{array}{l} \text{Demand :} \\ \text{Supply:} \end{array} \quad \begin{array}{l} q_t^d = \alpha_1 p_t + \alpha_2 x_t + \epsilon_{dt} \\ q_t^s = \beta_1 p_t + \epsilon_{st} \end{array}$$

Linear Combination of Demand and Supply

$$\begin{aligned} q_t &= \lambda q_t^d + (1-\lambda)q_t^s \\ &= [\lambda\alpha_1 + (1-\lambda)\beta_1] p_t + \lambda\alpha_2 x_t + [\lambda\epsilon_{dt} + (1-\lambda)\epsilon_{st}] \end{aligned}$$

Structural Form

$$\begin{aligned} \text{Demand :} & \quad q_t = \alpha_1 p_t + \alpha_2 x_t + \epsilon_{dt} \\ \text{Supply:} & \quad q_t = \beta_1 p_t + \beta_2 w_t + \epsilon_{st} \end{aligned}$$

Reduced Form

$$p_t = \frac{\alpha_2 x_t}{\beta_1 - \alpha_1} + \frac{\beta_2 w_t}{\beta_1 - \alpha_1} + \frac{\epsilon_{dt} - \epsilon_{st}}{\beta_1 - \alpha_1} = \pi_1 x_t + \pi_3 w_t + v_{1t}$$

$$q_t = \frac{\beta_1 \alpha_2 x_t}{\beta_1 - \alpha_1} + \frac{\alpha_1 \beta_2 w_t}{\beta_1 - \alpha_1} + \frac{\beta_1 \epsilon_{dt} - \alpha_1 \epsilon_{st}}{\beta_1 - \alpha_1} = \pi_2 x_t + \pi_4 w_t + v_{2t}$$

$$\beta_1 = \frac{\pi_2}{\pi_1} \quad \alpha_1 = \frac{\pi_4}{\pi_3} \quad \alpha_2 = \pi_1(\beta_1 - \alpha_1) \quad \beta_2 = \pi_3(\beta_1 - \alpha_1)$$

Structural Form

$$\begin{aligned} \text{Demand :} & \quad q_t = \alpha_1 p_t + \alpha_2 x_t + \epsilon_{dt} \\ \text{Supply:} & \quad q_t = \beta_1 p_t + \beta_2 x_t + \epsilon_{st} \end{aligned}$$

Reduced Form

$$p_t = \frac{\alpha_2 x_t}{\beta_1 - \alpha_1} + \frac{\beta_2 x_t}{\beta_1 - \alpha_1} + \frac{\epsilon_{dt} - \epsilon_{st}}{\beta_1 - \alpha_1} = \pi_1 x_t + v_{1t}$$

$$q_t = \frac{\beta_1 \alpha_2 x_t}{\beta_1 - \alpha_1} + \frac{\alpha_1 \beta_2 x_t}{\beta_1 - \alpha_1} + \frac{\beta_1 \epsilon_{dt} - \alpha_1 \epsilon_{st}}{\beta_1 - \alpha_1} = \pi_2 x_t + v_{2t}$$

$$\beta_1 = ? \quad \alpha_1 = ? \quad \alpha_2 = ? \quad \beta_2 = ?$$

Structural Form

$$\begin{array}{l} \text{Demand :} \\ \text{Supply:} \end{array} \quad \begin{array}{l} q_t = \alpha_1 p_t + \epsilon_{dt} \\ q_t = \beta_1 p_t + \epsilon_{st} \end{array}$$

Reduced Form

$$p_t = \frac{\epsilon_{dt} - \epsilon_{st}}{\beta_1 - \alpha_1} = v_{1t}$$

$$q_t = \frac{\beta_1 \epsilon_{dt} - \alpha_1 \epsilon_{st}}{\beta_1 - \alpha_1} = v_{2t}$$

$$\beta_1 = ? \quad \alpha_1 = ? \quad \alpha_2 = ? \quad \beta_2 = ?$$

Structural Form

$$\begin{aligned} \text{Demand :} & \quad q_t = \alpha_1 p_t + \alpha_2 x_t + \alpha_3 p'_t + \epsilon_{dt} \\ \text{Supply:} & \quad q_t = \beta_1 p_t + \epsilon_{st} \end{aligned}$$

Reduced Form

$$p_t = \frac{\alpha_2 x_t}{\beta_1 - \alpha_1} + \frac{\alpha_3 p'_t}{\beta_1 - \alpha_1} + \frac{\epsilon_{dt} - \epsilon_{st}}{\beta_1 - \alpha_1} = \pi_1 x_t + \pi_3 p'_t + v_{1t}$$

$$q_t = \frac{\beta_1 \alpha_2 x_t}{\beta_1 - \alpha_1} + \frac{\beta_1 \alpha_3 p'_t}{\beta_1 - \alpha_1} + \frac{\beta_1 \epsilon_{dt} - \alpha_1 \epsilon_{st}}{\beta_1 - \alpha_1} = \pi_2 x_t + \pi_4 p'_t + v_{2t}$$

$$\beta_1 = \frac{\pi_2}{\pi_1} \quad \beta_1 = \frac{\pi_4}{\pi_3} \quad \alpha_1 = ? \quad \alpha_2 = ? \quad \alpha_3 = ?$$

Linear Combination of equations (1) and (4)

$$(4) - [\theta_{13}/\theta_2] (1) =$$

$$y_1 - [\theta_{13}/\theta_2] y_2 + \theta_{14} y_4 + [1 - \theta_3 \theta_{13}/\theta_2] x_1 = 0$$

Equation (2):

$$y_1 + \theta_5 y_2 + \theta_6 y_4 + \theta_7 x_1 = 0$$

RANK CONDITION

$$\begin{vmatrix} y_3 & x_2 & x_3 \\ \theta_2 & 0 & 0 \\ \theta_9 & \theta_{10} & \theta_{11} \\ \theta_{13} & 0 & 0 \end{vmatrix} \neq 0$$

Reduced Form

$$p_t = \frac{\alpha_2 x_t}{\beta_1 - \alpha_1} + \frac{\varepsilon_{dt} - \varepsilon_{st}}{\beta_1 - \alpha_1} = \pi_1 x_t + v_{1t}$$

$$q_t = \frac{\beta_1 \alpha_2 x_t}{\beta_1 - \alpha_1} + \frac{\beta_1 \varepsilon_{dt} - \alpha_1 \varepsilon_{st}}{\beta_1 - \alpha_1} = \pi_2 x_t + v_{2t}$$

$$\varepsilon_{dt} = v_{2t} - \alpha_1 v_{1t} \quad \varepsilon_{st} = v_{2t} - \beta_1 v_{1t}$$

$$\begin{aligned} \mathbb{E} \varepsilon_{dt} \varepsilon_{st} &= \mathbb{E} v_{2t}^2 + \alpha_1 \beta_1 v_{1t}^2 - (\alpha_1 + \beta_1) \mathbb{E} v_{1t} v_{2t} \\ &= \sigma_2^2 + \alpha_1 \beta_1 \sigma_1^2 - (\alpha_1 + \beta_1) \sigma_{12} = 0 \end{aligned}$$

$$\alpha_1 = \frac{\beta_1 \sigma_{12} - \sigma_1^2}{\beta_1 \sigma_1^2 - \sigma_{12}}$$